



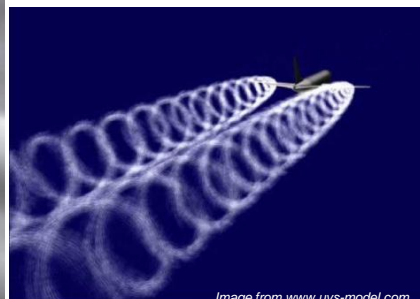
Fiber Laser Coherent LIDAR for Wake-Vortex Hazard Detection

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Fibertek Inc. , Herndon VA



This work is funded by NASA Langley Research Center





Introduction



Image from www.tc.gc.ca



Applications for airborne Coherent Lidar

- Aircrafts are flying “blind” with respect to atmospheric hazards
 - Wake-vortices
 - Turbulence
 - Air drafts
 - Wind-shear , etc.

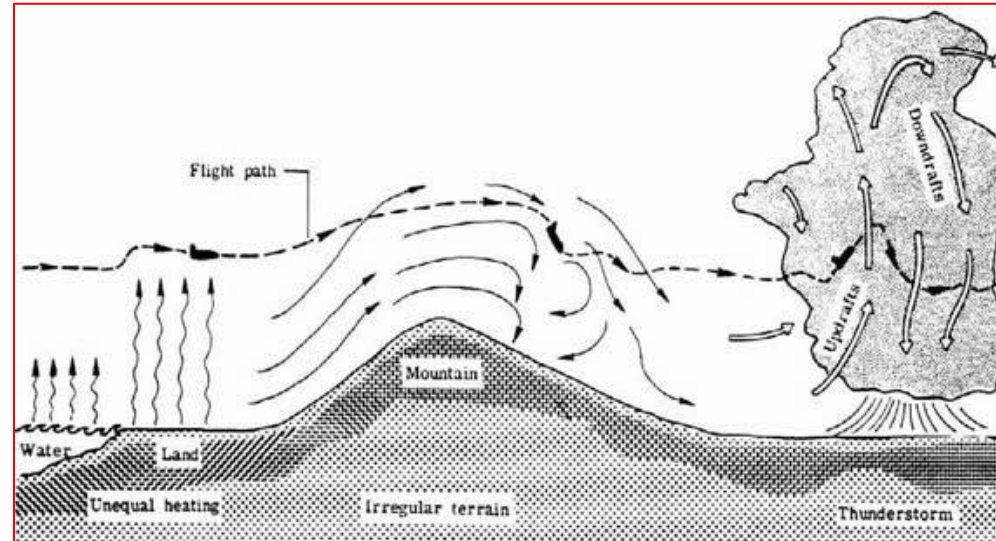
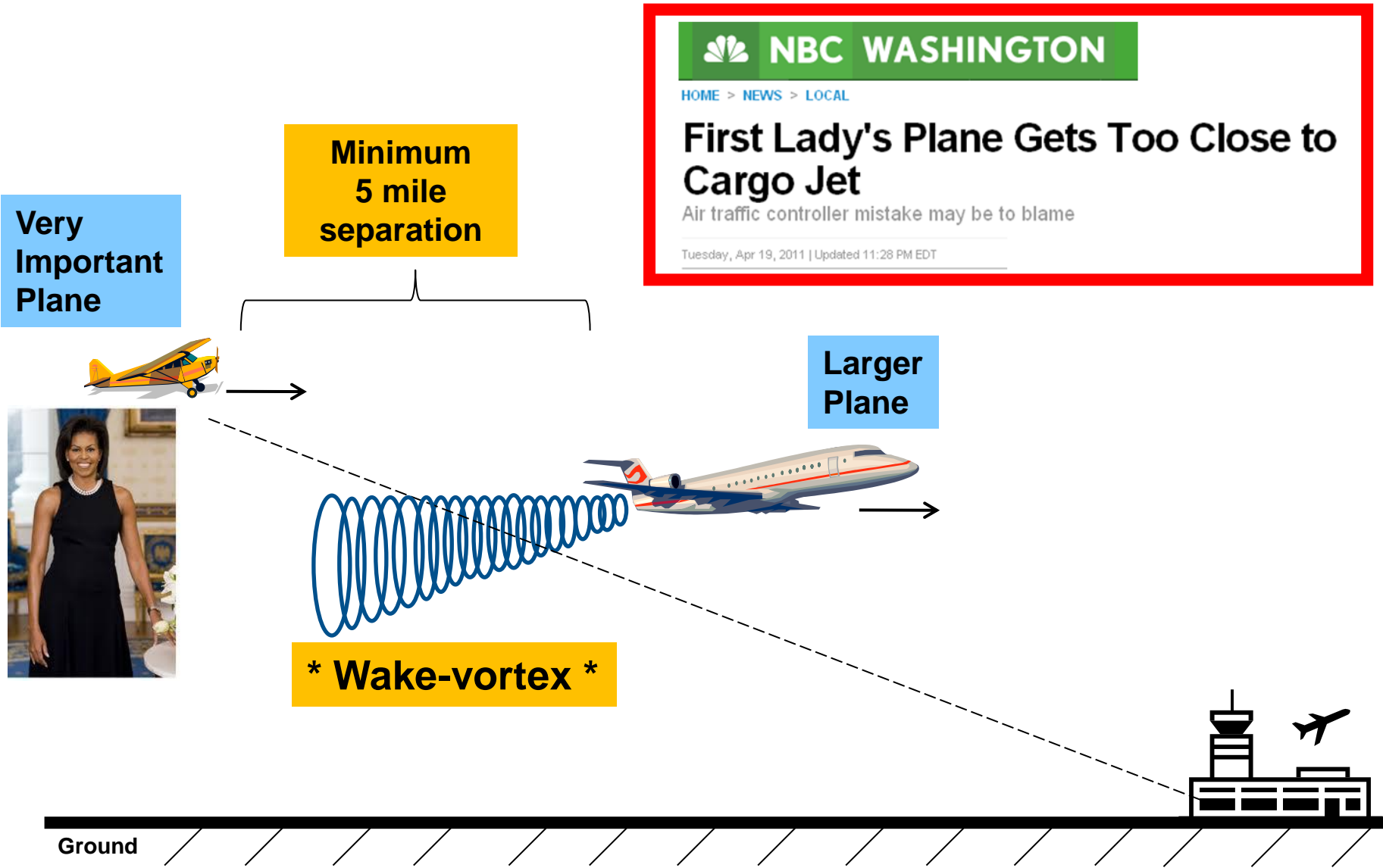


Image from www.aviationexplorer.com

- Airborne laser radar sensors can be useful for:
 - Atmospheric hazard detection
 - Flight pattern and Airport traffic optimization
(Reduced fuel consumption , optimized spacing)

Wake-Vortices at airports



NBC WASHINGTON
HOME > NEWS > LOCAL
First Lady's Plane Gets Too Close to Cargo Jet
Air traffic controller mistake may be to blame
Tuesday, Apr 19, 2011 | Updated 11:28 PM EDT

Very Important Plane

Minimum 5 mile separation

Larger Plane

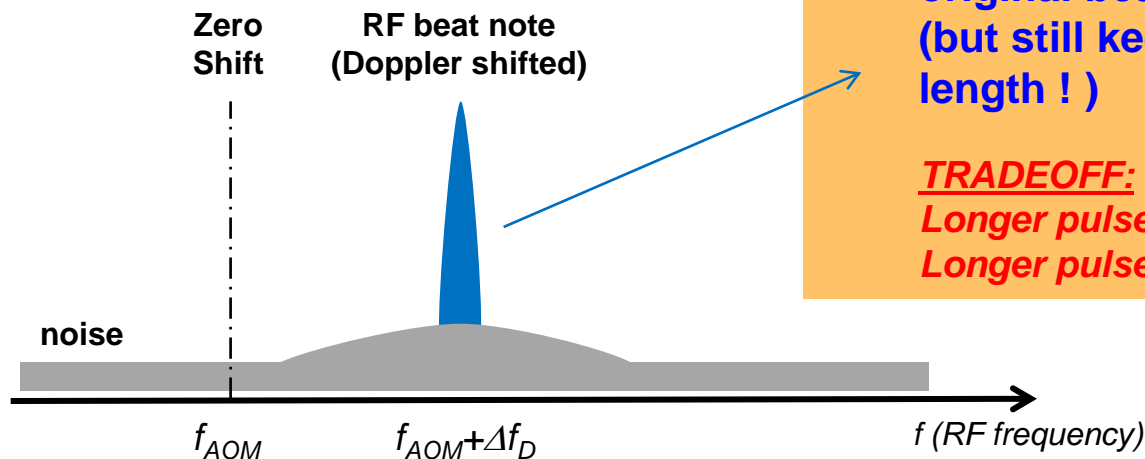
* Wake-vortex *

Ground



Coherent LIDAR theory

- Doppler frequency shift is proportional to line-of-sight wind vector for $1.55 \mu\text{m}$,
$$\Delta f_{\text{DOPPLER}} (\text{MHz}) \cong 1.29 \times V_{\text{WIND}} (\text{m/s})$$
- Noise and Broadening on the coherent RF beat note
 - Original optical linewidth , Pulsing of the laser Tx , Laser AM and PM noise
 - Photodetection noise (shot, thermal, etc.)
 - RF timing and amplifier noise , sampling/digitizing/windowing noise
 - Atmospheric effects



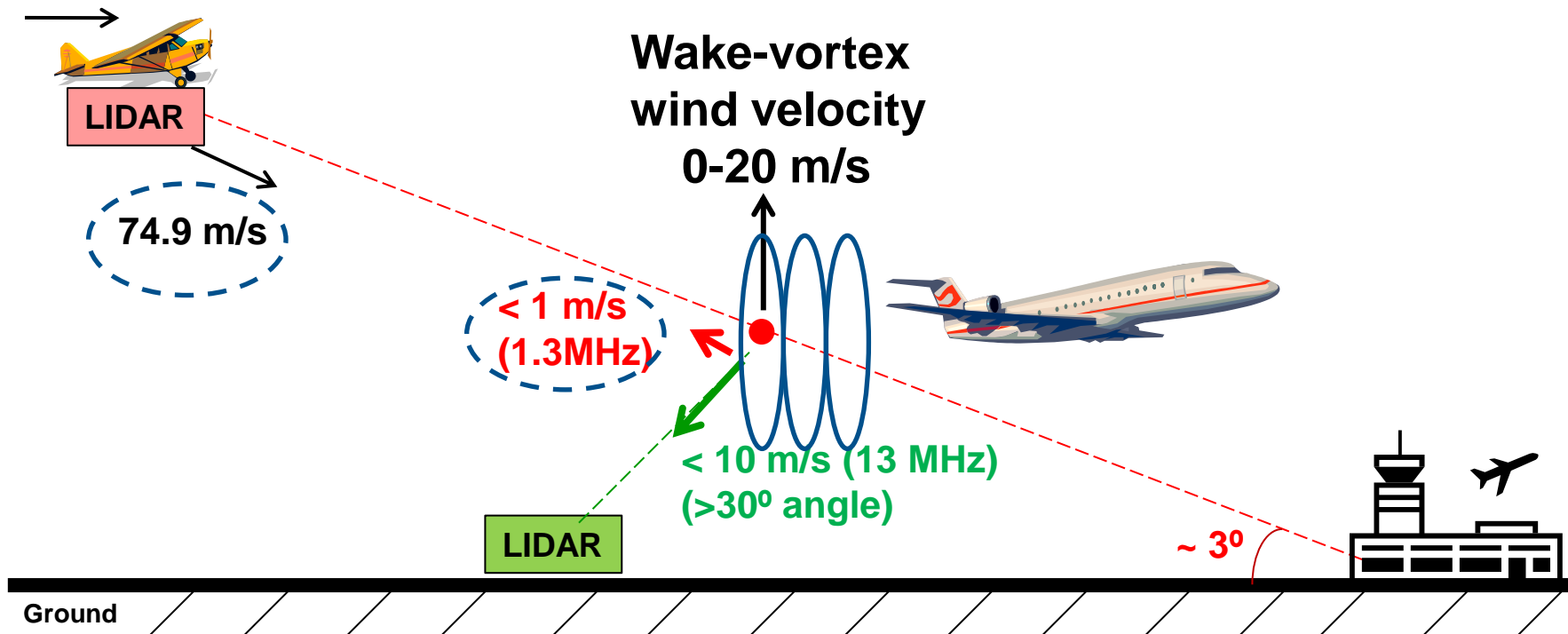
800 ns pulse broadens ~4 kHz original beat note to ~1.3 MHz (but still keeps original coherence length !)

TRADEOFF:
 Longer pulse - smaller linewidth
 Longer pulse - worse spatial resolution

Challenges for airborne Wake-Vortex LIDAR

- Forward-looking airborne wake-vortex measurement
 - Axial line-of-sight reduces dynamic range (Need very fine resolution)
 - Need accurate measurement of platform speed, attitude, etc.
 - SWaP and Cost limitations (multi-function instrument ?)
 - Dynamic wake trajectories and other atmospheric effects
 - Scanning geometry limitations (dynamic observer)

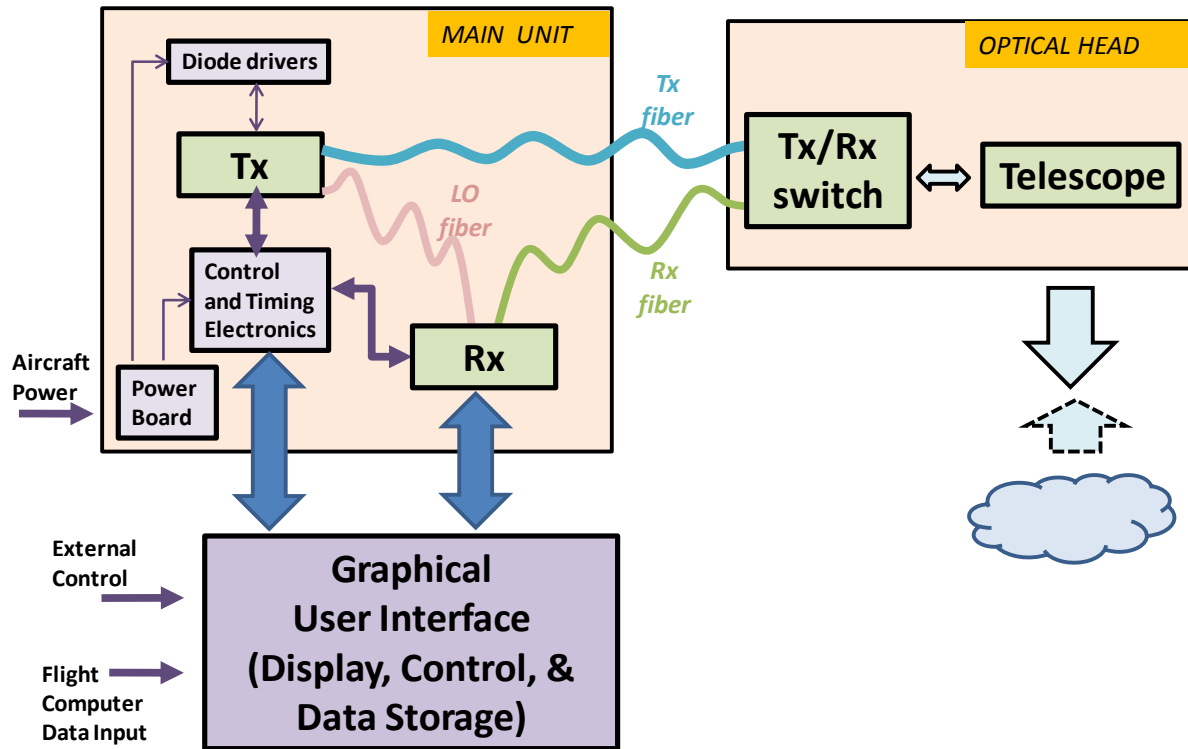
Landing Speed
~75 m/s



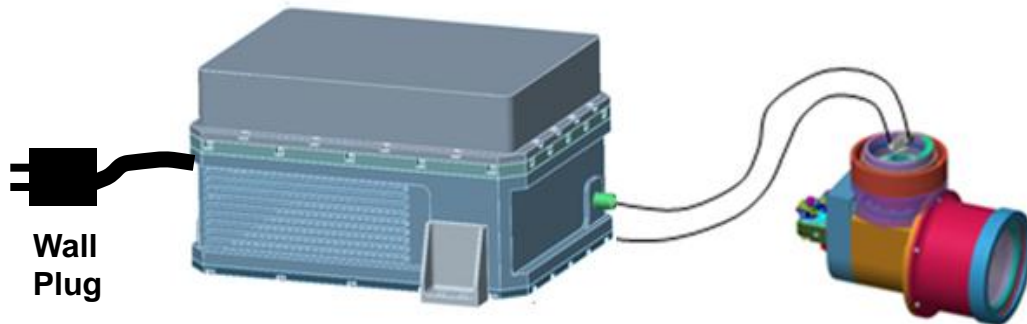


Coherent Lidar Transceiver Development

Coherent LIDAR system level details



- Eye-safe, all-fiber 1550 nm
- Two-piece design
 1. Main unit:
 - Includes Tx, Rx, and all electronics
 2. Optical head
 - Includes Tx/Rx switch, telescope
- Forced-air cooling



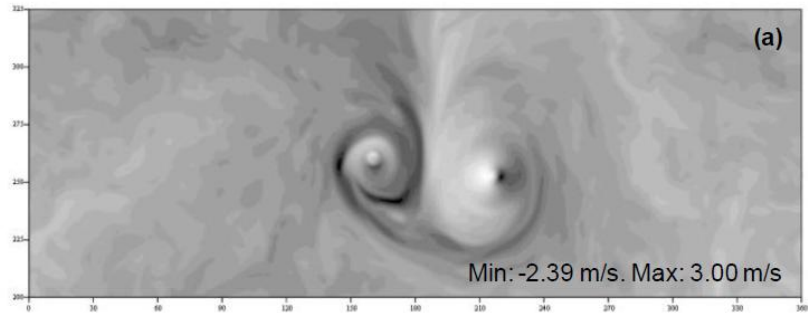
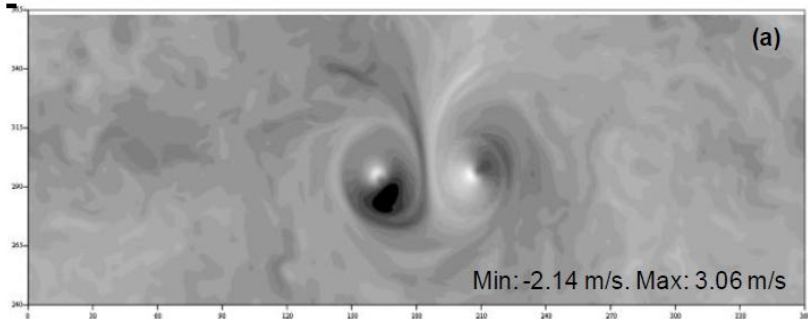
SWaP goals

Main unit: < 12"x10"x7"
< 30 lbs
Total: < 600 W power

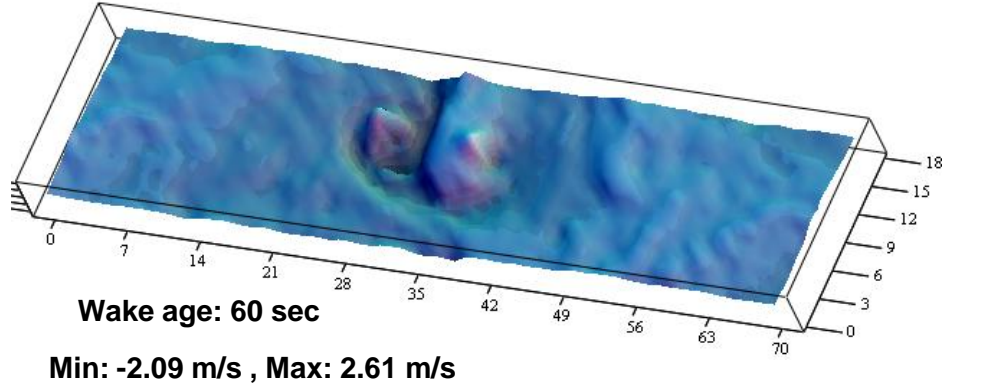
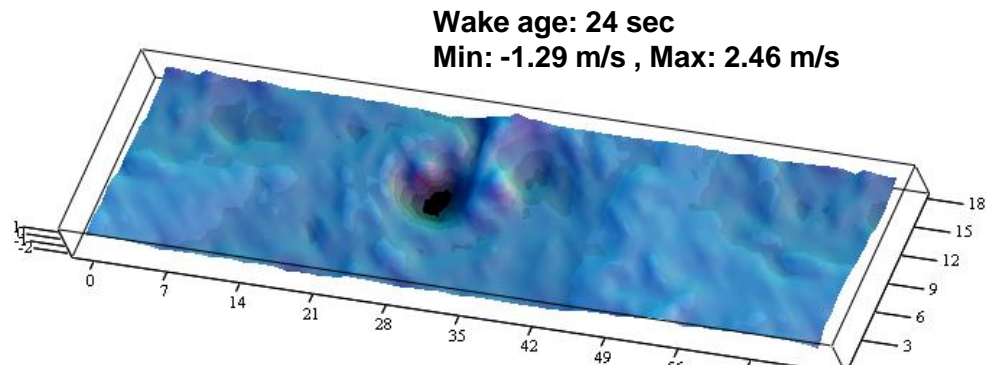
LIDAR performance simulations

- TASS data for a Boeing-747 landing supplied by NASA

TASS Data
($<1.25\text{m}$ x-y resolution)



Fibertek LIDAR
Scan simulations
($<7\text{m}$ x-y resolution)



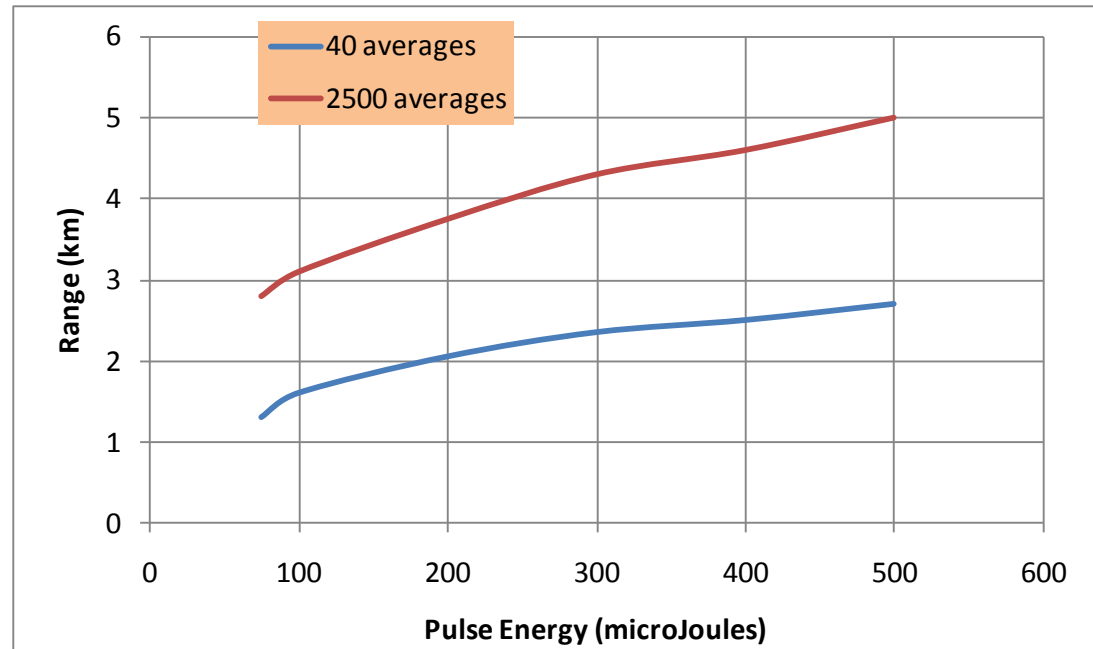


Range versus energy estimation

- 25 kHz rep. rate
- 5cm Rx aperture
- Final SNR=6

- **40 averages**
(>600 Hz data)
 - 120 μ J , ~1.7 km
 - 500 μ J , ~2.7 km

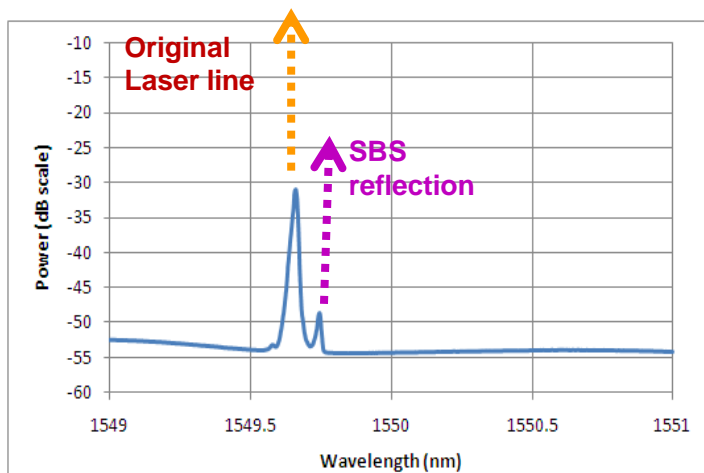
- **2500 averages**
(10 Hz data)
 - 120 μ J , ~3.2 km
 - 500 μ J , ~5 km



Fiber-Optic Lidar Transmitter (Tx)

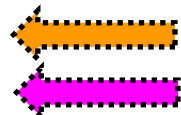
Performance limitations

- Fiber lasers optimal for
 - High average power, High repetition rate, Narrow linewidth, Flexible operation, Data modulation capabilities, Wall-plug efficiency, SWaP metrics, Production cost and repeatability
- Fiber lasers not optimal for
 - High energy (~mJ single mode), high peak power (~MW short pulse)
- Stimulated Brillouin Scattering (SBS) is the main energy-limiting factor for long pulses (800ns in this case)
 - Energy goes backward stealing gain and causing catastrophic damage
 - SBS threshold \equiv Equal peak levels backward (< 35 dB below forward)



~1mW total

Normal
backscatter



**SBS
reflection**

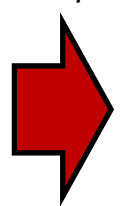
100mW

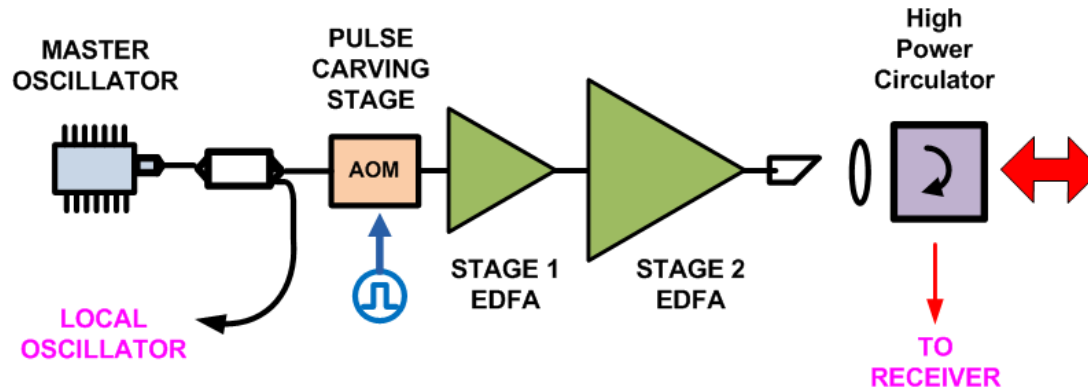
Input



10W

Output



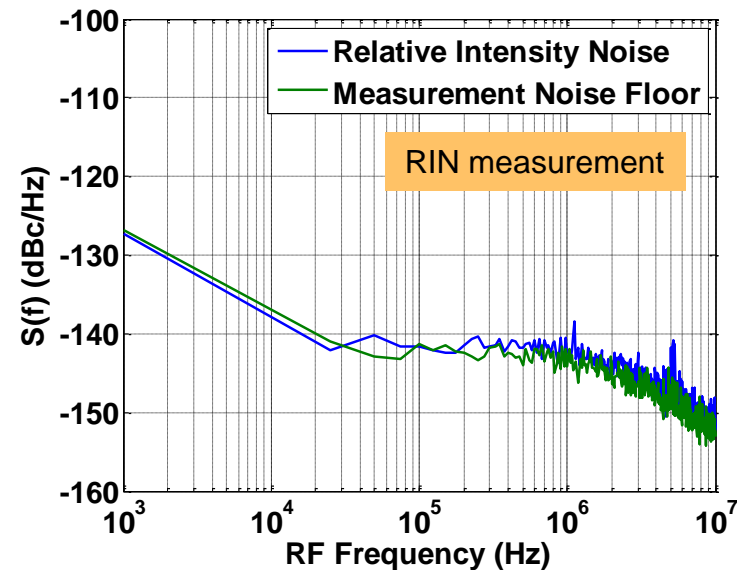
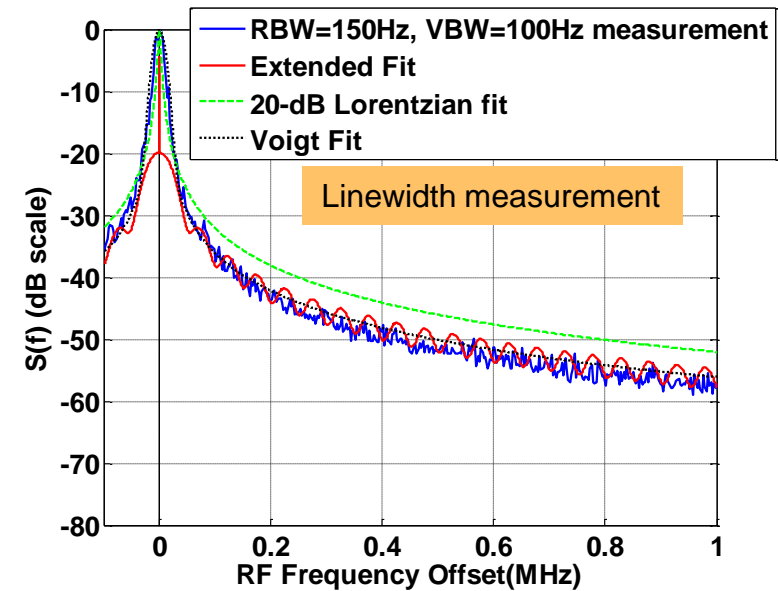
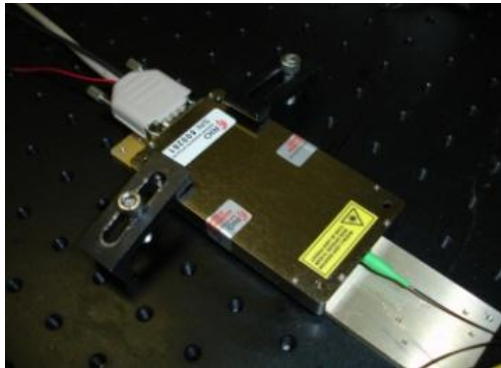


- Eye-safe 1550 nm wavelength
- Master Oscillator Power Amplifier (MOPA) Architecture
 - Ultra-low noise Master Oscillator
- Acousto Optic Modulator (AOM) for pulsing
 - High extinction ratio Pulse Carving
 - Optical frequency shifting of TR/REC with respect to LO
- All PM Erbium-doped fibers for amplification
 - Multi-stage MOPA for lowest noise with highest gain
 - Increasing MFD at each stage, COTS LMA fibers
- Proprietary techniques for SBS mitigation



Lidar Tx – Master Oscillator

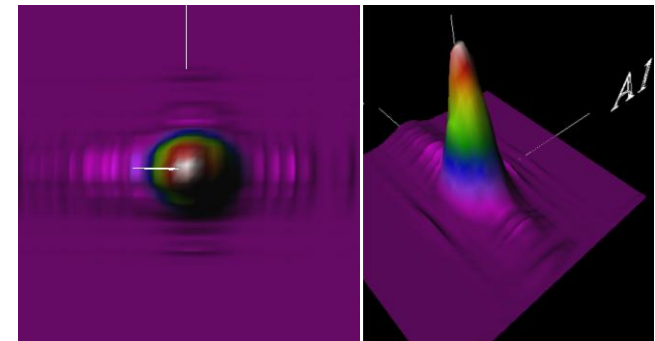
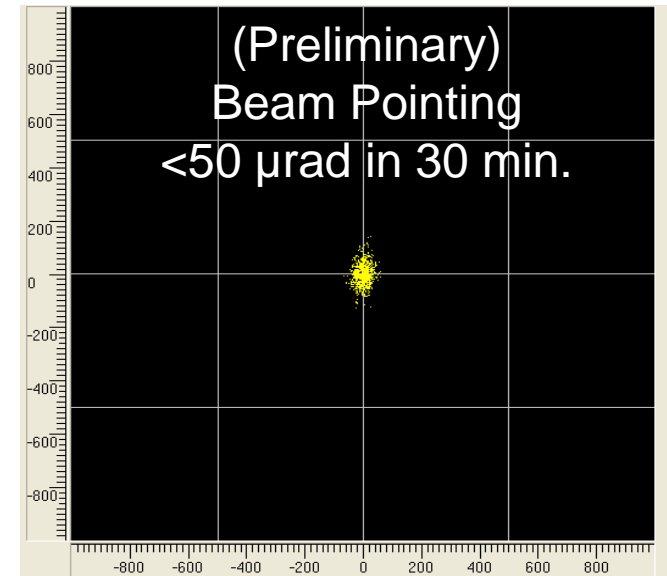
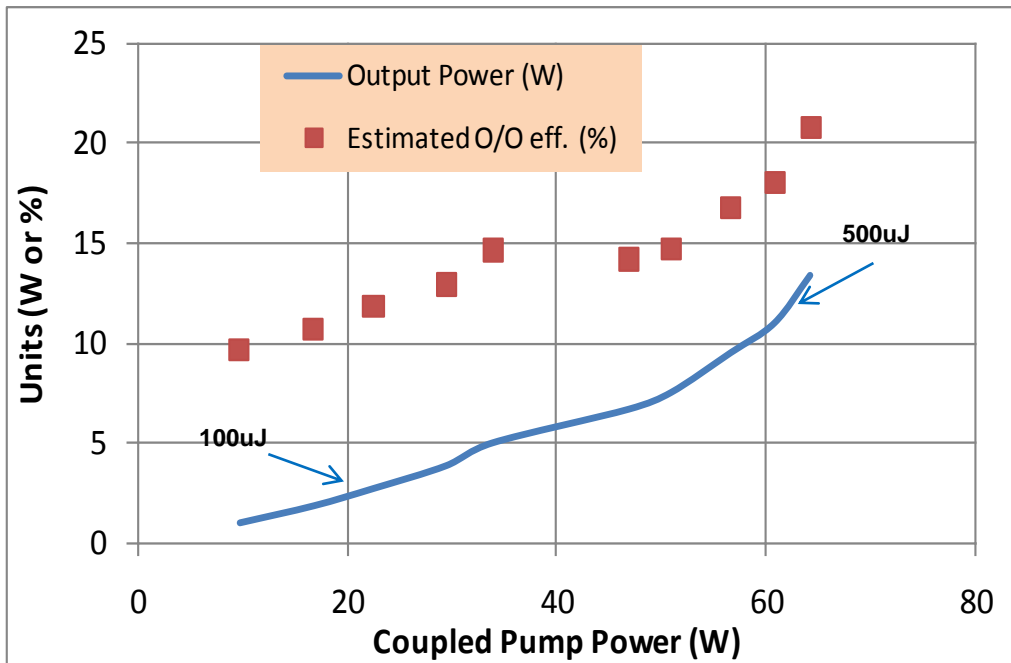
- Ultra-low noise 1550nm master oscillator (RIO Inc.):
 - Semiconductor + PLC based
 - ~2.5 kHz linewidth
 - -140 dBc/Hz RIN noise
 - SWaP efficient
- Pulsed with external AOM at 25 kHz, 800 ns pulse width





Lidar Tx – Power Amplifier

- PM LMA commercial Er-doped fiber
- Up to ~65 W coupled pump
- Up to ~14 W output power (~21% eff.)
- ~17 dB PER measured
- Single Mode ($M^2 < 1.2$) , stable pointing (even with bare fiber tip and standard optic mounts)





“Standard” SBS mitigation strategies

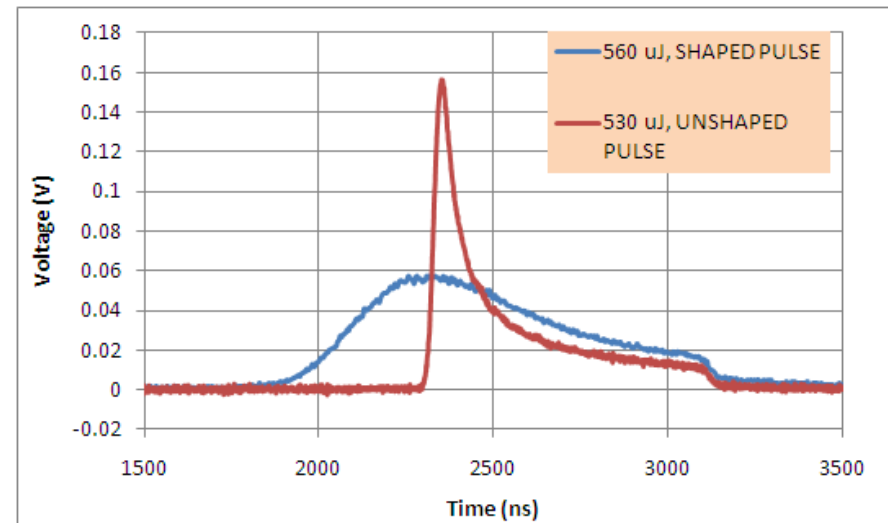
1. Input SBS threshold and output power depends on GAIN

- Increase Gain to increase SBS threshold
- TRADEOFF: Too much gain causes parasitic lasing

$$\text{Input SBS Threshold} = \text{CONSTANT} \times \ln(\text{GAIN})$$

2. Pulse steepening due to very long pulses

- Reduces SBS threshold and LIDAR resolution
- Pre-emphasis shaped pulse instead of rectangular shape (non-optimized)



3. Other techniques

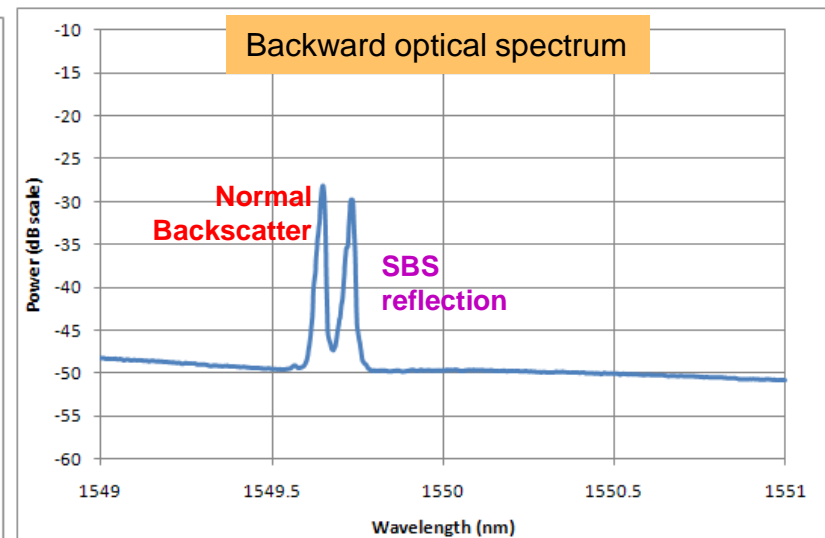
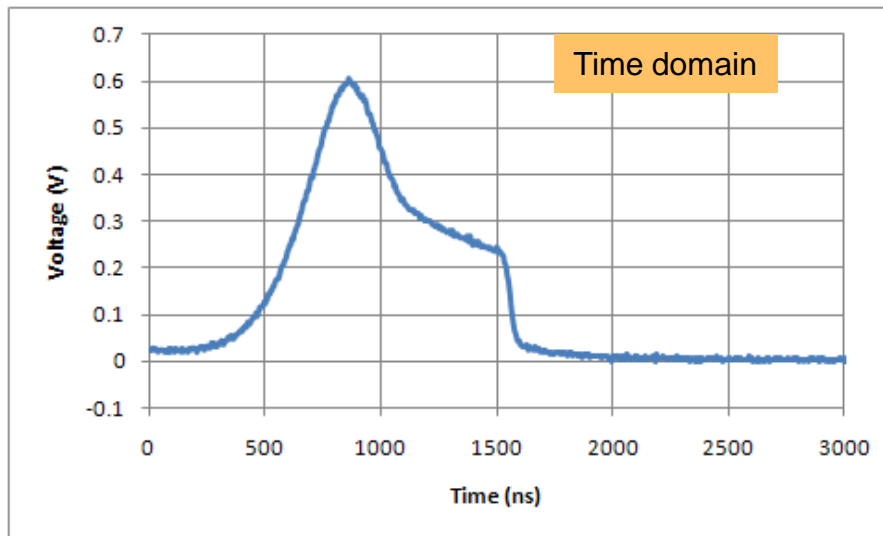
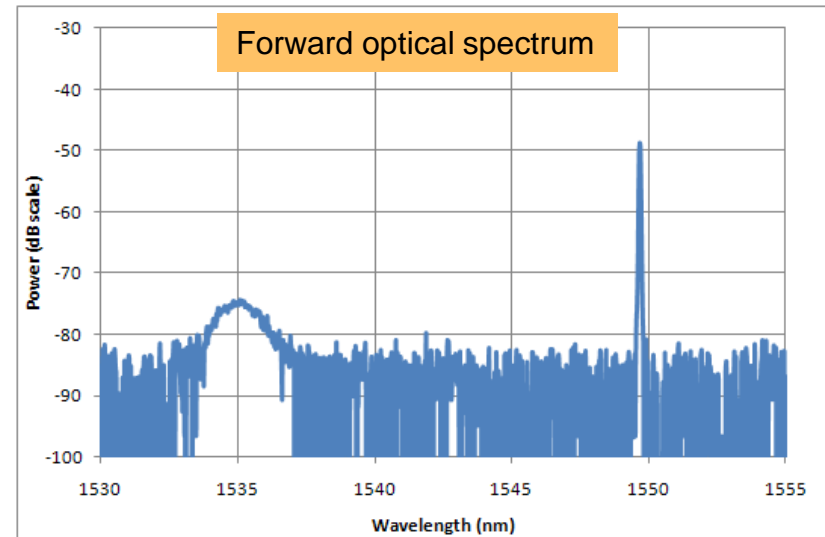
- Counter-pumping (reduces L_{eff})
- SBS-mitigated fibers (acoustic-tailored, temperature-tuned, segmented, etc.)
- Specialty VLMA fibers (photonic-crystal, multi-core, leaky channel, HOM, highly doped, etc.)

Tx output with “standard” SBS mitigation

Gain optimization and Pulse Shaping

- Increased gain in amplifiers while controlling ASE levels
- Implemented pre-emphasis pulse shaping (non-optimized)

120 μJ @ 25kHz
220 μJ @ 10kHz
at SBS threshold and low ASE

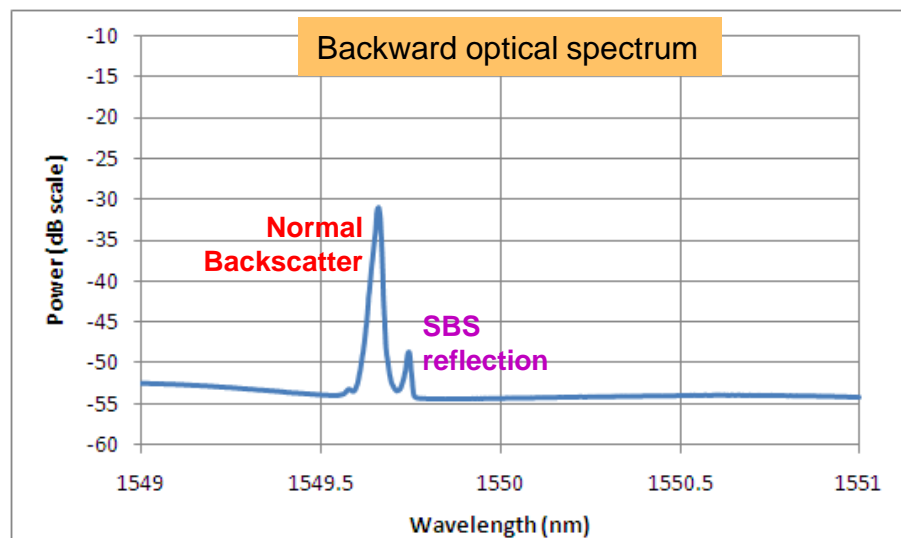
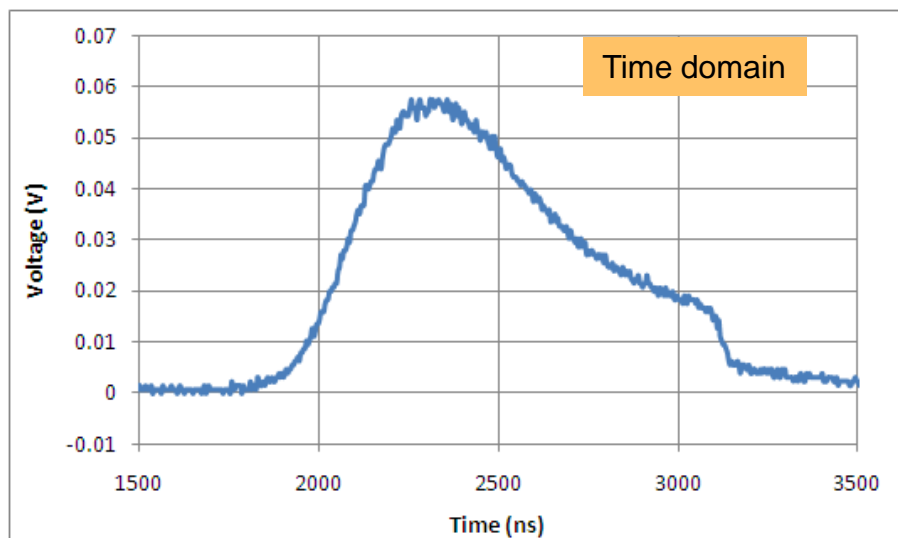
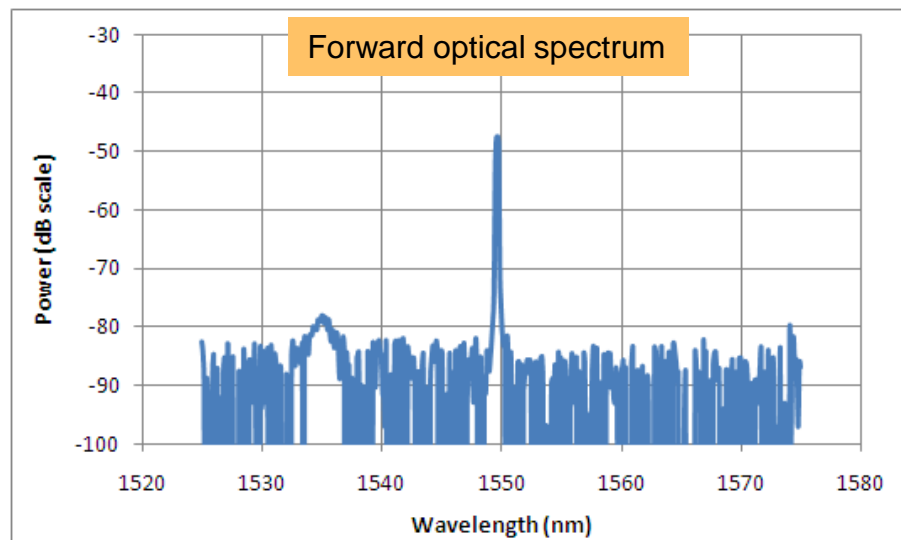




Tx output with “advanced” SBS mitigation

- Proprietary Fibertek techniques
- SBS threshold increase beyond standard methods

560 μJ @ 25kHz
800 μJ @ 10kHz
(pump limited)
with minimal SBS and ASE





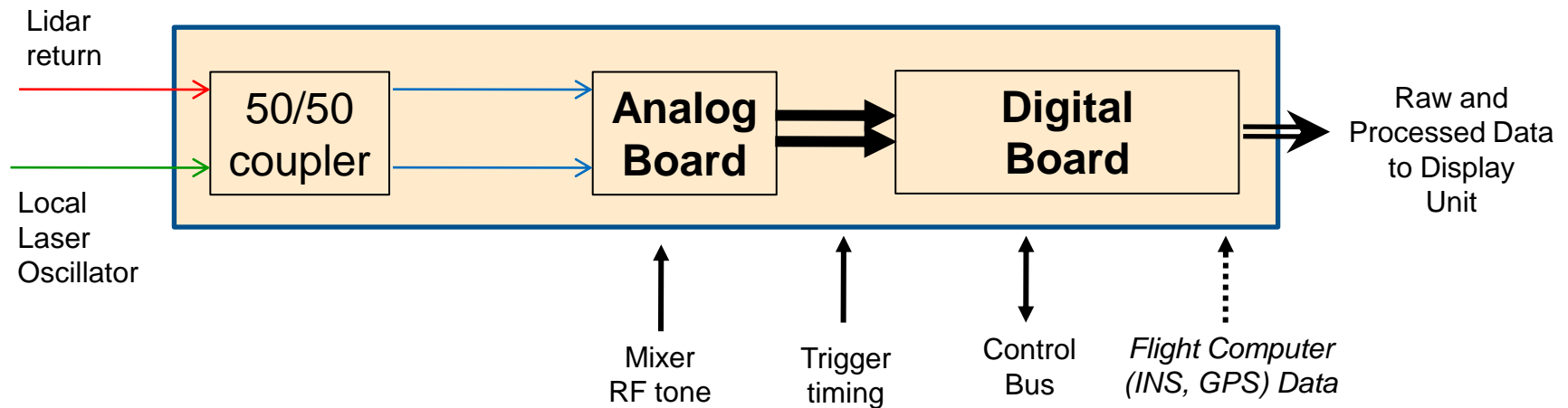
Survey and simple comparison

- LIDAR performance figure-of-merit (FOM) for fixed Rx aperture:

$$FOM = ENERGY \times \sqrt{PRF}$$

		LIDAR Vendor-Model	Energy (mJ)	PRF (Hz)	FOM
Solid State	}	LM-CTI WindTracer	2	500	45
		LM-CTI WindTracerX	5	500	112
		NASA-LaRC DAWN	250	10	790
Erbium fiber	}	Onera-Leosphere	0.12	12000	13
		ENRI-Mitsubishi	0.2	4000	13
		<u>Fibertek 120 μJ standard</u>	<u>0.12</u>	<u>25000</u>	<u>19</u>
		<u>Fibertek 220 μJ standard</u>	<u>0.22</u>	<u>10000</u>	<u>22</u>
		<u>Fibertek 560 μJ advanced</u>	<u>0.56</u>	<u>25000</u>	<u>88</u>
		<u>Fibertek 800 μJ advanced</u>	<u>0.80</u>	<u>10000</u>	<u>80</u>

Receiver (Rx) Design



- Receiver is comprised of two parts:
 - Analog board (Coherent, balanced photodetection, Platform velocity correction)
 - Digital board (Gs/s sampling , Real-time DSP and curve-fitting, I/Q, Gb/s data interface)
- Analog board sensitivity of ~ **2 fW** (SNR=6)
- Wind velocity measurement range of **± 20 m/s** with **~0.1 m/s** resolution
 - Airborne platform velocity correction of ~20 – 200 m/s (data read from external GPS)
- **~40-120m** range slice resolution
- <3.5 sec. data refresh rate (40 pulse avg., ~2000 pixels for certain scanning geometries)



Preliminary Lidar Testing

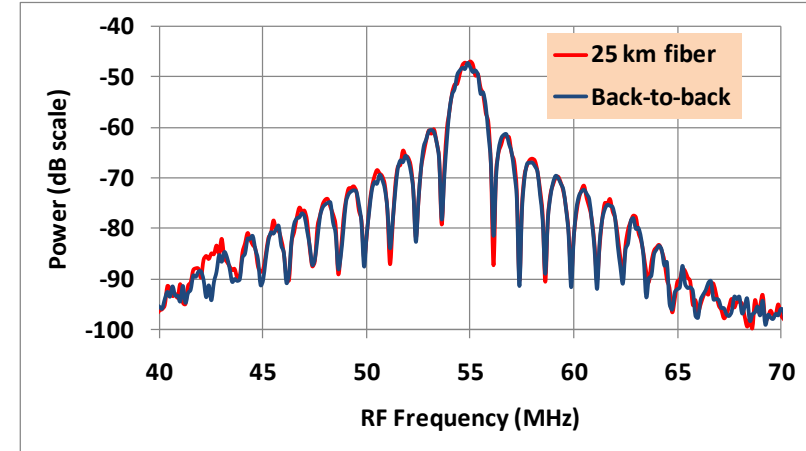
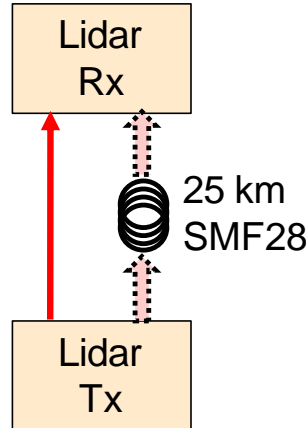


Lidar Tx + Rx – Preliminary lab experiments

1. Compare back-to-back and 25 km of SMF28 delay

- ~18.5 km range in air
- ~1 μ W received power (40 pJ)
- Zero Doppler shift=55 MHz

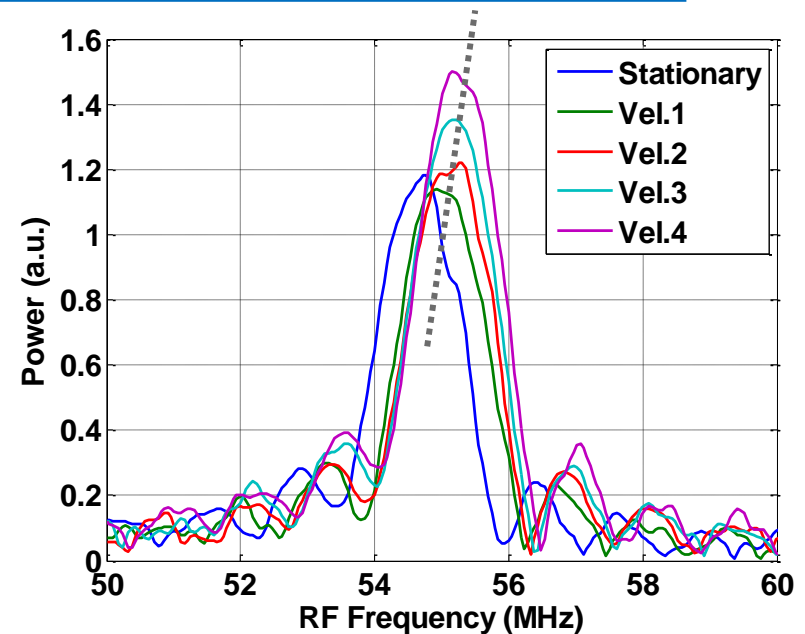
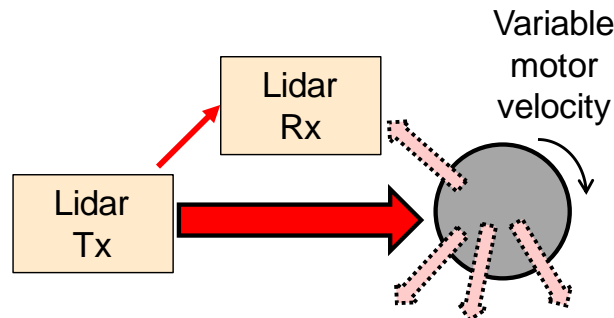
✓ Coherence Length



2. Test with variable target velocity and partially-completed receiver

- ~0.1 MHz (< 0.1 m/s) resolution
- ~100 pW received power (4 fJ)

✓ Sensitivity
✓ Resolution





Conclusions

- We present a fiber-optic, eye-safe Coherent LIDAR transceiver
 - 560 μ J of energy at 25 kHz rate, 800 μ J@10kHz (pump limited)
 - 800 ns pulsewidth with <3kHz local oscillator optical linewidth
 - ~2 fW estimated receiver sensitivity with >2 km range
 - Velocity measurement of ± 20 m/s with ~0.1 m/s resolution
 - Desirable SWAP metrics for airborne platform
- We believe that this lidar can be a useful tool for airborne wind sensing, turbulence and wake-vortex detection